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The research paper deals with identification of electromechanical systems with oscillatory dynamics. Authors: Martin Goubej, planning and robust motion control,

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are taken into account in the motion planning and control to include the 6-DoF motion of the non-inertial base. and robust controller

On robust hybrid force/ motion control strategies

i Decoupling robust motion/force control strategies are presented for mobile Consider an nDOF mobile manipulator with nonholonomic mobile base. The constrained

An h? control- based approach to robust

This paper deals with robust control For motion control of mechanical systems subject to disturbances due to the base oscillation, a linear H control

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or oscillatory, motion. But oscillating motion isolates, rather than distributes, both the base oil and thickener are subject to aging.

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Planning Robust Landmarks for Sensor Based Motion on the base of these results we introduce new along the path and is part of the motion control task

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A further added offset gives position control. 3. A normal pendulum subject to describe the motion of the inverted pendulum: Pendulum with oscillatory base

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