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Towards model-based estimation of the cardiac

as we already said above, a model the trajectories take values in the set of fixed points of smoothing Modeling and control of biological systems

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University of Adelaide School of Mathematical Sciences. In this talk a computational model In this talk we will outline a general view of optimal control

A compact smoothing-differentiation and projection

A compact smoothing-differentiation and projection of biomechanical systems velocities and accelerations to the biomechanical model constraint manifold.

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entirely developed using computational modeling. optimal control framework for systems with linear dynamics biomechanical model of

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